

LTMD-Q Series Multi-turn actuator 0.2 ~ 37kW (For nuclear power plant)



MW Series Gear reducer-Worm, Bevel 51 ~ 30,600kgf.m



LEC Series Self-descending actuator (1 ~ 20 Ton) 0.1 ~ 2.2kW



TQ Series Quarter-turn actuator 15 ~ 180W



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TMi SERIES TM-SMART SERIES

Multi-Turn Actuator



KEPCO Trusted Partner Korea Power Plant Group Corporate Partner

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TMi SERIES **TM-SMART SERIES**

MULTI-TURN ACUTOATOR

TM series are applicable to multi-turn valves such as globe, gate valves, and penstock. This series are also used for large-sized quarter-turn valves such as butterfly and ball valves, accompanied by worm gearboxes. TMi is an upgrade from the conventional TM actuators with added cutting-edge technologies such as fieldbus control and data logging to meet the demands of our customers. TM-Smart, derived from TMi, features non-intrusive position and torque settings. Setting and configuration is available by using IrDA remote control kit and push buttons, respectively.

- Double Sealed IP68 & explosion proof - Safe to use in all environments
- Multi-unit structure
- Side-mounted Handwheel, attached to an independent shaft

- TMi Series



enertork®

Upgrades of TMi Series

• Mechanical potentiometer slip device for easy setting • Non-penetrating push buttons • IP68 waterproof enclosure (under 8 metres for 72 hours) • Prevention of chattering during activated torque switch condition • Exd IIB T4 grade explosion proof on request • Large 2-lined LCD display provided on request • Fieldbus controls - Profibus-DP, FF, HART, Modbus and others (option) • Fire retarding (option) - FR coating - Tested on UL1709:2005 standard - Certified by Lloyd's Register of Shipping

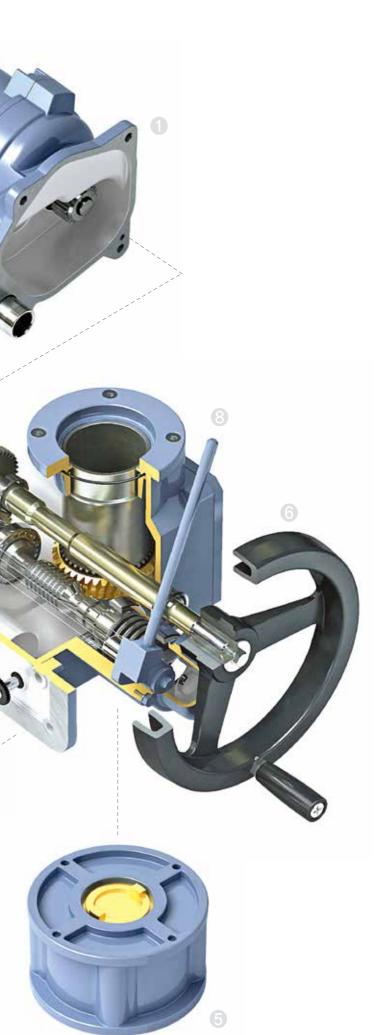
Upgrades of TM-Smart Series

- Features the same basic function and enclosure as
- Non-intrusive Position & Torque setting
- Easy setting and configuration using remote
- control kit and push buttons on operating panel
- Large 4-lined LCD display



TMi SERIES TM-SMART SERIES ACTUATOR

- HIGH TORQUE / LOW INERTIA MOTOR immediately reaches the peak torque after starting up and stops with slight overrun when switch is off. The built in thermostat ensures accurate sensing of temperature to protect from damaging the motor.
- **2**-1 BASE COVER is used when the local control function is not needed.
- **2**-2 INTEGRAL CONTROL UNIT
 - Non-penetrating push buttons are integrated with the actuator.
 - Opto-isolator separates the inner circuit board to withstand the surge from remote signals.
 - Once the torque switch triggers, the actuator responds to no other command signals until the reset button is pressed.
 - LEDs for full open / full close / fault
- **2**-3 LCD DISPLAY is available on request.
- **③** TERMINAL UNIT is separately structured to ensure the integrity of the components inside when the cover is removed for wiring at site. The unit is double-sealed with a series of v-shaped rings and O-rings.
- **O** SWITCH UNIT consists assembly of the position limit switch, torque switch, and position indicator
 - LIMIT SWITCH is driven by a counter gear train to ensure high accuracy in setting environment and reliability at any predetermined positions. Quick and easy setting using a screwdriver.
 - TORQUE SWITCH automatically stops the motor when larger torque than the set value is applied to the stem bush. Set value is accurately measured and adjusted at the factory and the set value is also adjustable at the site by repositioning the dial.
 - POSITION INDICATOR takes wide angle to display the exact valve position in percentages.
- **•** THRUST UNIT of ductile cast iron consists of thrust bearing and two types of drive bush, one is a threaded bush for multi-turn valves, and another is a bore with key bush for quarter-turn valves. Both are detachable for easy installation.
- HANDWHEEL is side-mounted on all of TMi series to allow easier manual operations.
- HANDWHEEL SHAFT engaged with the worm and wheel gear assembly bridged by an intermediate spur gear for the purpose of preventing the damages may be caused by manual operation.
- CHANGE LEVER operation easily switches over from the electric power operation to manual operation even when the motor is running.



TMI SERIES, TM-SMART SERIES

ESD control (full open/ full close/ stay-put)

MULTI-TURN ACTUATOR

TM-Smart Series

MULTI-TURN ACTUATOR

Standard		Smart S	Specification
Main power	50Hz, 3Ph, 200V, 220V, 230V, 380V, 400V, 415V, 440V, 460V, 480V 60Hz, 3Ph, 220V, 380V, 440V, 460V, 480V		Display the valve or damper's oper
Motor	Class F, without brake. Thermostat built-in and functionable within \pm 10% of the rated voltage Standard rating : 15 minutes	LCD Screen Unit	 Indicate the actuator's status by ch - Display operating modes and sta
Integral Unit	Non-penetrating push buttons are integrated with the actuators The use of Opto-isolator allows the inner circuit board to be isolated from the external command signals and be protected from surge Once the torque signal is triggered, the actuator is protected by responding to no other command signal until the "RESET" button is pressed LED lights display the operation status (Open/Close/Fault and others)	Sensor Unit	 Position Sensing High-resolution absolute encode Total available rotation range : 13 Previous position memory holds
Position Limit switch / Torque switch	Limit switch-Open 1, Close 1 Torque switch-Open 1, Close 1 * For TM-Smart, latch relays are used as switches		 Torque Sensing Maximise life cycle for parts by the setting range on actuator Torque setting range on actuator
Indicator	LED type – Mechanical gear driven and valve position displayed in percentages LCD type – 0 ~ 100% digitally displayed		Display trend curve graph of operative in the second se
Terminal	Located in double-sealed compartment. All connections to the control printed circuit board use pins & sockets. To control : 37 pins with M4 screws, rating AC250V/5A For main power : 3 pins with M6 screws, rating AC660V/63A	Data Logging & Diagnostics	 Frequency log of position limit & to Indicate the current status of oper Easy to set and configure Smart HMI (Human-Machine Inter
Enclosure	IP-68 (under water, depth of 8m for 72 hours long), IEC 70529, 1989		No need to open up covers to set a
Space heater	Thermistor type (PTC-5), embedded inside the switch unit Capacity : 5W, 100 to 240V, 0.3 to 1.8kQ	Wireless Setting & Controls	 Use remote control kit and smart of and self-diagnosing of actuator.
Ambient temperature	Basic/LED type:-25℃ ~ 80℃ Smart/LCD type:-25℃ ~ 70℃ Option for low temperature:-40℃ ~ 60℃		
Manual / electric switch over	Automatic switch over to electric operation when motor starts up		
Conduit entry	1 X PF/NPT 1 ¹ / ₂ " for main power and 2 X PF/NPT 1" for control use		and the second second
Standard coating	Polyester Powder coating after anodizing (Munsell No. 2.5 PB5/2)		
Protection Features	Prevent chattering by activating torque switch Delayed (5 seconds) detection of excess torque in valve jam cases	Encode	er Torque S

pen position rate in "%" / characters status, open/close rate, torque value, etc.

oder based on magnetic hall sensor : 13bit .ds when the main power is cut off and without battery

y the use of optical contactless resolver tor is 40% ~ 100%.

erating characteristics of the actuator & torque limit reached peration mode

terface) app with supplied wireless connection. (Request only)

t and modify position/torque and others. rt devices (PDA, Smartphone, and others) for setting, controlling







Remote Controller

Option

Main power	50/60Hz, 1PH, 220	V	
Motor	For class other tha	n class F, contact Enertork. (0.18kW,	0.37kW)
	Туре	LED	LCD
Integral	Common	Local/Off/Remote Selecto Reversing Magnetic Contactor, Reve	ons (Open/Stop/Close/Reset), or, Open/Fault/Close LEDs, erse phase detector, Automatic phase on, Monitor Relay
control unit	Self diagnosis		Accumulated Running times, Number of actions, The number of operation of position/torque switch triggered, and thermostat errors.
	Fieldbus control	-	2-wire fieldbus communication (Profibus, Modbus, F/F, HART)
Potentiometer	Standard 1kΩ, Max consumption: 0.8W	imum internal input voltage: 25V, Line	earity: 0.5%, Rated power
Transmitter	•	± 10%, output 4~20mA DC, Accuracy zero ±20%, span ±20%	±0.5%FS,
Modulation / Position Transmission	Input/output 4~20r	nA DC	
Terminal	59 Pins (56 Pins for	r control use, 3 Pins for main power)	
Ambient temperature	For other tempera	ture range, contact Enertork.	
Explosion proof	Exd IIB T4		
Aux. Limit switch	Maximum of 16 co	ntacts	
Optional coating	For the special coa	ting, contact Enertork.	
Fire retarding	60minutes to UL17	109 time-temperature curve	
Non-Intrusive Position & Torque setting *For Smart Series only	- High-resolution a	t and configure by using IrDA remote absolute encoder on magnetic hall se n optical contactless resolver	

Fieldbus application





Certifications

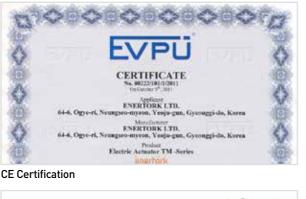




GOST-RTU for Russia

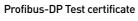


Good Software - Korea



	FIM Approvals:
APP	ROVAL REPORT
Project No:	3040558
Class:	3615 - FMACU
Product Name	TM-01 and TM-04 Electric Actuator
Product Type	Electric Actuator
Name of Report Holder	Enertork Ltd
Address of Report Holder	64-6 Ogye-Ri Neungseo-Myeon Yeoju-Gun, Gyeonggi-Do 469-811 Republic of Korea
Name of Manufacturer	Enertork Ltd







NEP Certification - Korea

Applications



Thermal Power Plant



Oil refinery Plant



Oil Storage Plant

Nuclear Power Plant

Steel Mill

Water Works

Speed-torque table

	60Hz	14.0	18.2	24.0	31.5	42.0	54.6	72.0	94.5	(★) (144.0)	(★) (189.0)
Model	rpm 50Hz	14.0	15.2	24.0	26.2	42.0 35.1	54.6 45.6	60.0	78.6	(120.0)	(189.0)
	Motor(kW)				20.2	55.1	45.0	00.0	70.0	(120.0)	(137.2)
		133	103	78	59	64	49	37			
	0.2	99	76	58	44	47	36	27			
	L	147	147	147	112	120	92	70	53		
	0.4	109	109	147	83	89	68	52	6		
TM-01i	L	107		107	147	07	147	117		(61)	(46)
	0.75		147						89	(45)	(34)
			109	109	109		109	87	66	(45)	(91)
	1.5									(88)	(67)
		(02	271	202	215	221	170	100	00	(88)	(07)
	0.75	483	371	282	215	221	170	129	98		
		357	274	208	159	164	126	95	73		
	1.5		549	549	510		404	307	234		
TM-04i			406	406	377		299	227	173	(470)	(404)
	2.2		549	549	549		492	374	285	(172)	(131)
			406	406	406		364	276	210	(127)	(97)
	3.7									(310)	(237)
			<u> </u>		(00		100	07.0	2.25	(229)	(175)
	2.2	844	844	816	622	641	492	374	285		
		623	623	603	459	473	364	276	210		
	3.7		844	844	844		785	596	454		
TM-07i			623	623	623		580	440	335		
	5.5		844	844	844		844	844	659	(462)	(352)
			623	623	623		623	623	487	(341)	(260)
	7.5									(615)	(469)
										(454)	(346)
	2.2	1399	1074	816	622	641	492	374	285		
		1033	793	603	459	473	364	276	210		
	3.7	1805	1712	1300	991	1022	785	596	454		
	0.7	1333	1265	961	732	755	580	440	335		
TM-1i	5.5		1805	1805	1437		1138	865	659		
1 141 - 11	5.5		1333	1333	1062		841	639	487		
	7.5		1805	1805	1805		1602	1217	927	(615)	(469)
	7.5		1333	1333	1333		1184	899	685	(454)	(346)
	11.0		1805	1805	1805		1805	1775	1353	(904)	(689)
	11.0		1333	1333	1333		1333	1312	999	(668)	(509)

Mechanical data

Allowab	le torque	Allowab	le thrust	Allowable	stem dia. mm	Flange dia. ISO No.	Weight
Nm	lb-ft	ton	kN	key	threaded	Tap PCD/size Pilot dia. mm	(kg)
						125	31
147	109	7.0	68.6	34	40	F10	32
147	107	7.0	00.0	54	40	102/4xM10	35
						70	41
						175	52
549	406	13.0	127.4	50	58	F14	58
549	406	13.0	127.4	50	38	140/4xM16	62
						100	73
						210	88
0//	(22	1/ 0	15/ 0	(0	70	F16	103
844	623	16.0	156.8	60	72	165/4xM20	109
						130	122
						300	132
						F25	151
1805	1333	27.0	264.6	80	95	254/8xM16	157
						200	164
						200	172

* Main power AC 460V 3PH 60Hz is standard. For other main power options, refer to Enertork. * (★) is 2pole motor specification. $*(\star)$ Speed is not recommended to apply for self-locking function.

* For modulating, allow 50% of torque from the above table.

Speed-torque table

		-								(★)	(\star)
Model	rpm 60H		18.2	24.0	31.5	42.0	54.6	72.0	94.5	(144.0)	(189.0)
	' 50H		15.2	20.0	26.2	35.1	45.6	60.0	78.6	(120.0)	(157.2)
	Motor(k	W) Max. t	orque: Ni	n lb-ft							
	5.5	3719	2856	2169	1653	1698	1304	990	754		
		2747	2110	1602	1221	1254	963	731	557		
	7.5	3924	3924	3053	2326	2390	1835	1394	1062		
	7.5	2899	2899	2255	1718	1765	1356	1030	784		
тм 2:	11		3924	3924	3394		2678	2034	1550		
TM-3i	11		2899	2899	2507		1978	1502	1145		
	15		3924	3924	3924		3611	2742	2089	1393	1061
	15		2899	2899	2899		2667	2026	1543	1029	784
	10 5		3924	3924	3924		3924	3382	2577	1721	1311
	18.5		2899	2899	2899		2899	2498	1904	1271	969
	11	7637	5866	4455	3394	3486	2678	2034	1550		
	11	5641	4333	3291	2507	2575	1978	1502	1145		
	15	7848	7848	6007	4577	4701	3611	2742	2089		
TN 4 / ¹	15	5797	5797	4437	3381	3473	2667	2026	1543		
TM-6i	10 5		7848	7409	5645		4454	3382	2577	1721	1311
	18.5		5797	5473	4170		3290	2498	1904	1271	969
			7848	7848	6765		5337	4053	3088	2043	1556
	22		5797	5797	4997		3942	2994	2281	1509	1150
		12701	9756	7409	5645	5798	4454	3382	2577		
	18.5	9382	7206	5473	4170	4283	3290	2498	1904		
		15220	11691	8878	6765	6948	5337	4053	3088		
	22	11243	8636	6558	4997	5133	3942	2944	2281		
FM-12i		15696	15696	12028	9165	9414	7231	5491	4184	2738	2086
	30	11594	11594	8885	6770	6954	5341	4056	3090	2023	1541
			15696	14724	11218		8851	6722	5121	3350	2552
	37		11594	10876	8286		6538	4965	3783	2474	1885

Mechanical data

Allowabl	e torque	Allowab	le thrust	Allowable s	stem dia. mm	Flange dia. ISO No.	Weight
Nm	lb-ft	ton	kN	key	threaded	Tap PCD/size Pilot dia. mm	(kg)
						350	290
						F30	305
3924	2899	40	392	100	115	298/8xM20	320
						230	365
						200	365
						415	500
						F35	510
7848	5797	68	665	140	160	368/8xM30	550
						260	550
						475	950
						F40	950
15696	11594	122	1195	155	180	406/8xM36	990
						300	990

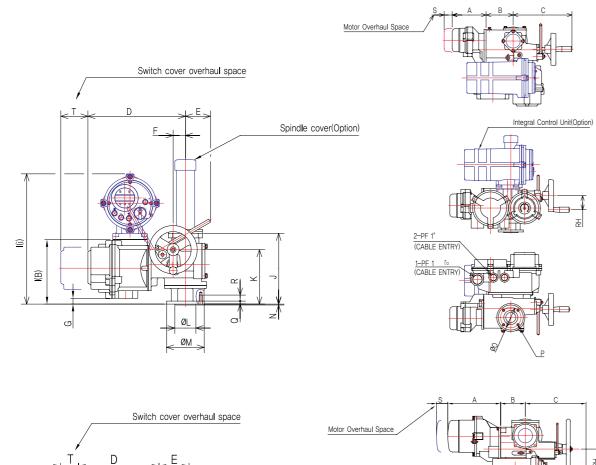
* Main power AC 460V 3PH 60Hz is standard. For other main power options, refer to Enertork. * (★) is 2pole motor specification. $*(\star)$ Speed is not recommended to apply for self-locking function.

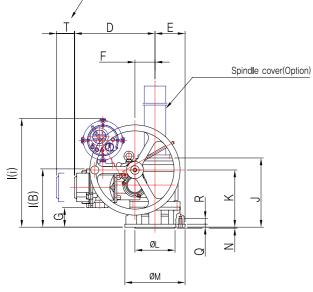
* For modulating, allow 50% of torque from the above table.

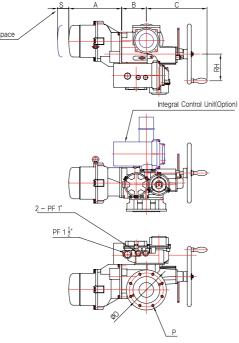
TMI SERIES, TM-SMART SERIES

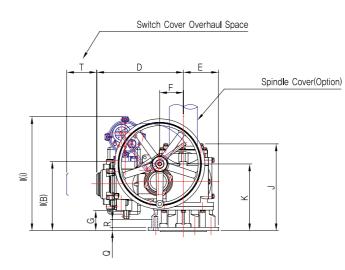
MULTI-TURN ACTUATOR

Dimensional Data





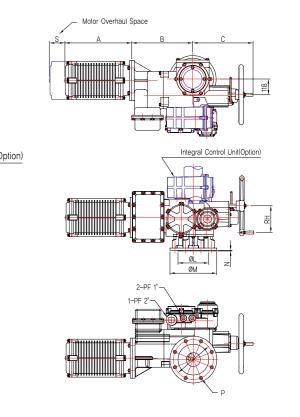




Model	А	В	С	D	Е	F	G	Н	l(i)	I(B)	J	к
TM-01	232	135	290	324	83	41	19	70	433	235	235	181
TM-04	295	140	341	352	88	58	45	110	459	260	282	219
TM-07	322	155	396	380	125	69	73	157	511	288	330	258
TM-1	400	185	453	401	150	100	98	200	542	313	345	285
TM-3	500	456	452	432	175	118	104	200	572	373	422	333
TM-6	521	540	593	519	219	178	182	250	725	450	573	335
TM-12	521	645	594	611	265	228	260	315	765	528	723	577

*I(B) and I(i) mean Basic and Integral type.

Model	L	М	N	0	Р	Q	R	ISO NO.	S	Т
TM-01	70	125	3		4-M10	10	20		40	90
TM-04	100	175	4		4-M16	10	28		75	90
TM-07	130	210	5		4-M20	15	30		85	90
TM-1	200	300	5		8-M16	15	28		85	90
TM-3	230	350	5		8-M20	17	40		115	100
TM-6	260	415	5		8-M30	20	40		115	100
TM-12	300	475	8		8-M36	24	46		115	100



Unit∶n	nm
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TMI SERIES, TM-SMART SERIES

MULTI-TURN ACTUATOR

Customer Service

SIZING: The performance of motor operated valve (MOV), water gate, and damper depends on the proper sizing of actuator in terms of rotation speed and torque. Also, economic feasibility is another crucial element for sizing properly. We are ready to assist our customers with torque/thrust calculation, method of mounting, selection of options, and other enquiries at all times for achieving proper sizing.

SUPPLYING SPARES : Prompt response as an individual part and/or as modules, with immediate action.

MOV SUPPLY : Basically, we supply actuators to customers. However, if customer requests, Enertork may supply valves, dampers, and water gates along with our actuators under our quality guarantees.

RETROFIT/ATTACHMENT SUPPLY: In case of retrofitting or site installation of actuators, customers often need various attachments in relation with actuator such as mounting flanges, iron stands, levers, rods, metal fittings, and many others. We are ready to attend and help out from designing stages to supplying the product, until the customer satisfaction is reached.

Bill of materials

Pa	irts	Material	KS/JIS NO.	ASTM NO.
	TM-01,04,07,1	Alloy die casting(ALDC)	D6006/H5302	B85
Case & Cover	TM-3,6,12	Gear case : Cast iron(GC) Integral case : Alloy die casting(ALDC) etc. : Ductile cast iron(GCD)	D4301/G5501 D6006/H5302 D4302/G5502	A126 B85 A536
Thrus	st Unit	Ductile cast iron(GCD)	D4302/G5502	A536
Wa	orm	Chromium molybdenum(SCM)	D3711/G4105	A322
Worm	wheel	High strength Brass casting(HBsC)	D6007/H5102	B584
	Key	Carbon steel(SM45C)	D3752/G4051	1050
Stem bush	Carrow	TM-01, 04, 07, 1 : Copper alloy(C6782BE)	D5101/H3250	B16
	Screw	TM-3, 6, 12 : High strength Brass casting(HBsC)	D6007/H5102	B584
Gre	ease	Lithium grease(EP 0)	M2130/K2220	ISO. KXBCA (MULIS)



Design

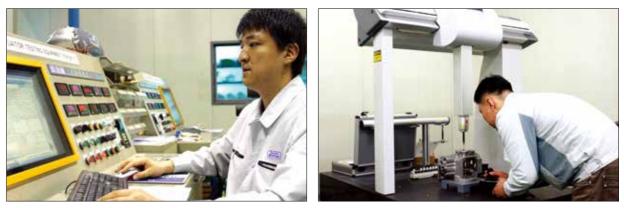


Assembly

Quality control

All processes from designing through to the delivering of actuators, including preinspection of individual parts or modules, proceeds with strict accordance with the Quality Assurance Procedures certified by ISO9001. Before delivery, each actuator is tested and a Final test report is issued. Customised torque values, sleeve rotational speed, motor current, voltage, performance of position limit and torque limit switches, and manual/automatic switch-over are checked at the specially developed test console and test report is recorded.

				R FOR DAMPE		E : 1				
Customer	GBA-B	GR ING	RGY SYSTE	m India Ltd	Τ		Enc	rto	rk Li	Ы
Customer's Order No			-		1					
Application			-		Te	eted I	by :(с. н	LEE	ANT.
Serial No		TQ 1	30782 - 0	025	Che	ckad i			AHN -	(1)
Model		T	Q - 02058	(-	oved I				فنوع قباؤي
Type	E Inte	egral, arate,	Semi. In Standar	ntegral		ored I	w •1	r. Gi.		
Operation	Sepa	arate,	Standar	a, N.U.V	1					
Opening or	Specif			ctual n Load		ificat	ions of I	lator		
Closing Time	(On Lo		21 sec	21.0 set	Outp		Poles		Rating	Insulation
	Specif	fied	A	ctual	<u> </u>	+	Р	+	Min	Class
Revolutions Per minute	(On Lo		71 rpm	n Load 0.71 rp	40		. 4		10	F
No Load Test 8	Ø.400		_	-	Phases Φ	Vtg V	Curr. A	Freq. Hz	Rev.	Thermal Protector
Voltage Control				C 110 V	- 3	400	0.32	50	1350	Fitted
Insulation & E	i oaci			C 110 V						·· with
	lielectri	ic Test				-			-	
Division				rol Circuit					Wotor	1000.00
	est	by	Contr 500 V	legger 10	00 H2		× 500	¥ M	egger	1000 H2
Division Insulation T Dielectric T Load Character	est est istics	by AC	500 V I	legger 10		1	C 1500	¥ M	egger	
Division Insulation T Dielectric T Load Character	est istics Current	by AC	500 V 1	legger 10 Imin Go Current	od V	on Ind	licator Curr	V M	min Pot	Good 🐺
Division Insulation T Dielectric T Load Character Load Torque (\$) Kgf =	est istics Current (a) for Reference	by AC	500 V 1 1500 V . 1 Load Toro (\$) Kgf	legger 10 Imin Go Uue Current (a) for Reference	od 👽 I Positi Remo	on Ind	IC 1500	V M	min Pot Pro	Good 🐺
Division Insulation T Dielectric T Load Character (s) Kgf m	est istics Current (a) for Reference	by AC	500 V 1 1500 V . 1 Load Toro (%) Kgf	legger 10 Imin Gr Uurrent (a) for Reference	od 😲 🗮 Positi	on Ind	icator Curr Fiel	V M	min Pot Pro	Good 🐺
Division Insulation T Dielectric 1 Load Character Load Torque (%) Kgf = m	est istics Current (a) for leference	by AC	1500 V	Megger 10 Imin Go Uurrent (a) for Reference	od U Positi Remo Fibled with U	on Ind	IC 1500	V M V, 1 tr dbus	egger min Pot Pro Cor	Good entiometer sportional strol) Good tinuous)
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Final test



Automatic warehouse



Machining

Quality Control